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(54) **CONTROLLING DRIVING MODES OF SELF-DRIVING VEHICLES**

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CPC ***B60W 50/082*** (2013.01); ***G05D 1/0061*** (2013.01); ***G05D 1/0088*** (2013.01); *B62D 1/286* (2013.01)

(58) **Field of Classification Search**
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(57) **ABSTRACT**

A computer-implemented method, system, and/or computer program product controls a driving mode of a self-driving vehicle (SDV). Sensor readings describe a current operational anomaly of an SDV that is traveling on a roadway. One or more processors compare a control processor competence level of the on-board SDV control processor that autonomously controls the SDV to a human driver competence level of a human driver in controlling the SDV while the SDV experiences the current operational anomaly. One or more processors then selectively assign control of the SDV to the on-board SDV control processor or to the human driver while the SDV experiences the current operational anomaly based on which of the control processor competence level and the human driver competence level is relatively higher to the other.

20 Claims, 8 Drawing Sheets